# ONE-DIMENSIONAL MODELS FOR TRANSPORT IN SOLID CYLINDERS

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## THIS WORK IS A BRIDGE BETWEEN TWO OLD PROBLEMS

### Admittedly, It Is An Incomplete Bridge

- The so-called Marshak wave problem is a classic problem in high-energy density radiative transfer.
  - Several variations of the problem exist, but the main theme is that a cold medium is subject to a source of radiation and a wave propagates through the medium.
  - The problem usually imagines a slab geometry configuration.
- One-dimensional models for particle transport in evacuated ducts has been used to model the transport of particles using a simplified model.
  - The transport in the duct is modeled using an effective scattering from the duct walls.
- There is active research in developing models for Marshak waves in configurations reminiscent of the duct problem.

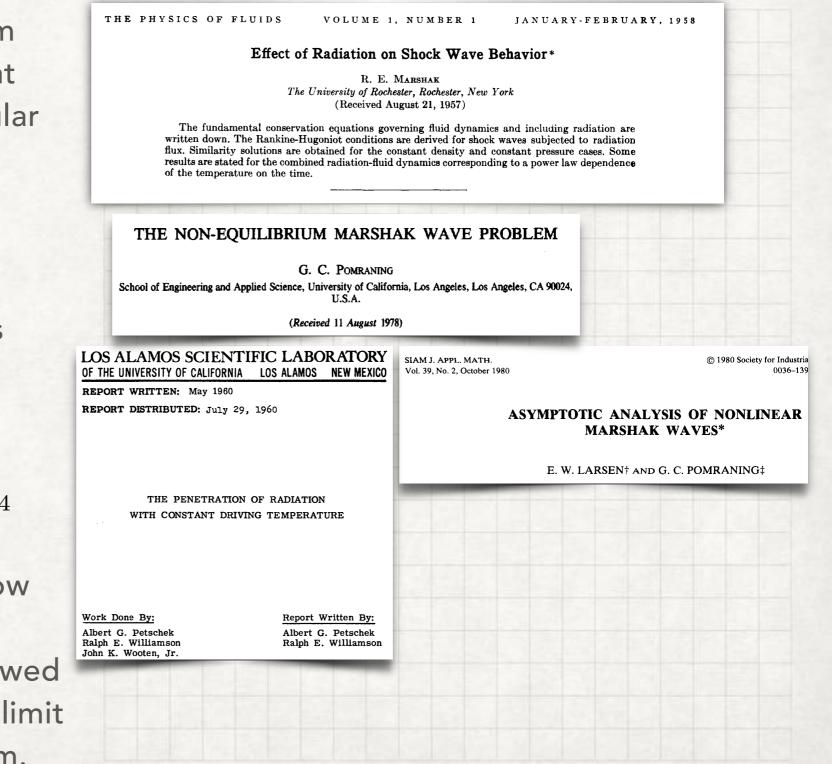
# THE MARSHAK WAVE PROBLEM

## The Classical Work

- The Marshak wave problem has a cold slab with an heat source applied at a particular point.
- Via radiative transfer the medium is heated.
- If the material is optically thick, as the original works assume, the governing equations is a nonlinear diffusion equation.

 $\frac{\partial e(T)}{\partial t} = \frac{\partial}{\partial x} \frac{1}{3\kappa(T)} \frac{\partial}{\partial x} acT^4$ 

- Petschek demonstrated how to find similarity solutions.
- Larsen and Pomraning showed that this is the asymptotic limit of a non-equilibrium system.



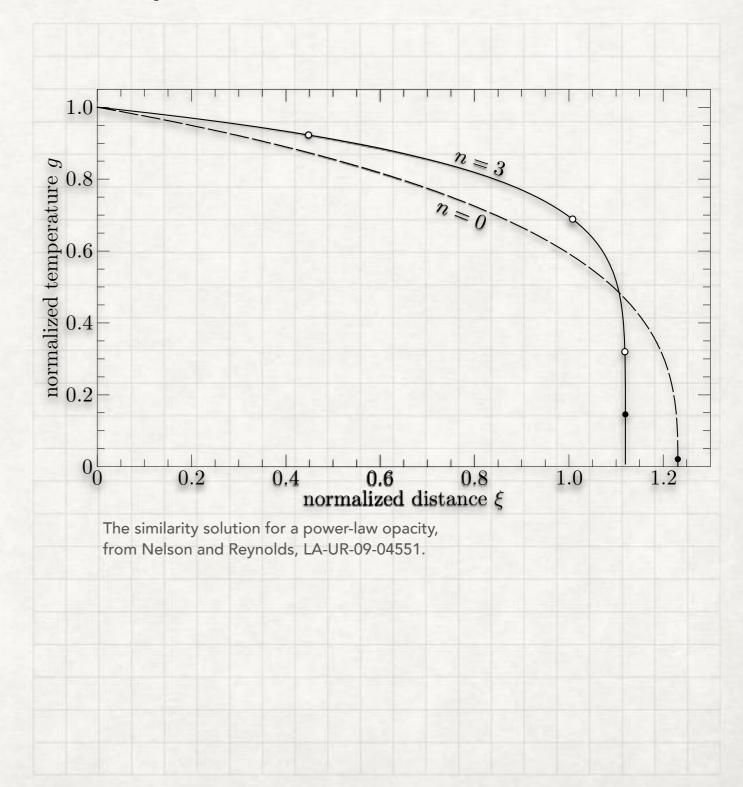
# SIMILARITY SOLUTION

### **Power Law Opacities**

- If the opacity has the form  $\kappa(T) = \kappa_0 T^{-n}$
- There exists a similarity solution  $T(\xi)$  where

$$\xi = C(n) \frac{x}{\sqrt{t}}$$

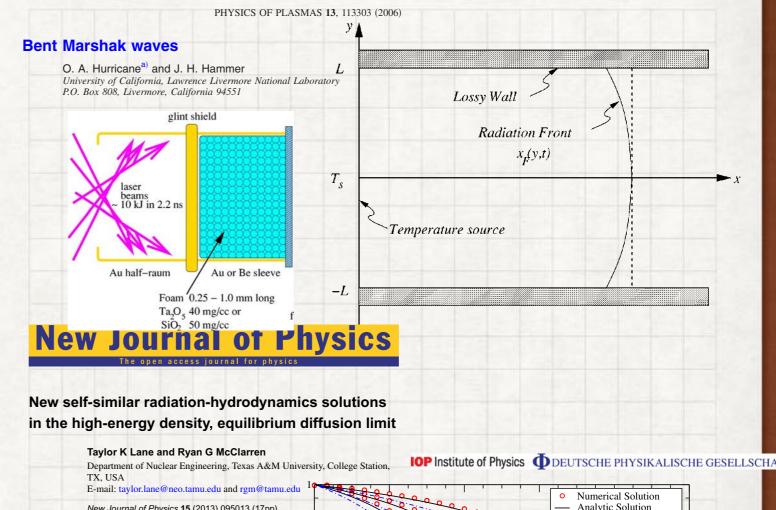
 The steepness of the wavefront is controlled by the power in the opacity.

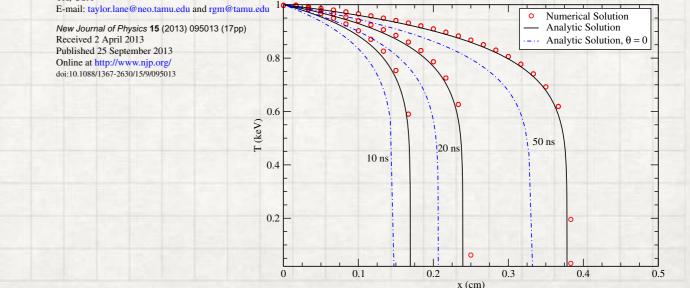


### EXPERIMENTS DO NOT HAVE SLABS WITH A CONSTANT DRIVING TEMPERATURE

### Drive Conditions And Radial Losses Change The Picture

- Hammer and Rosen extended the theory to include a nonconstant driving temperature.
- Hurricane and Hammer tried to account for radial losses in the model.
  - Use observation that away from wave front the material temperature changes slowly.
- Other work added radiation energy density terms and material motion into the model.





## DIFFUSION MODELS OF RADIATIVE TRANSFER IN FINITE SYSTEMS

- The Hurricane-Hammer model points out that behind the wave-front the time dependence of the solution is negligible.
  - This makes the problem here an 2-D Laplace equation.

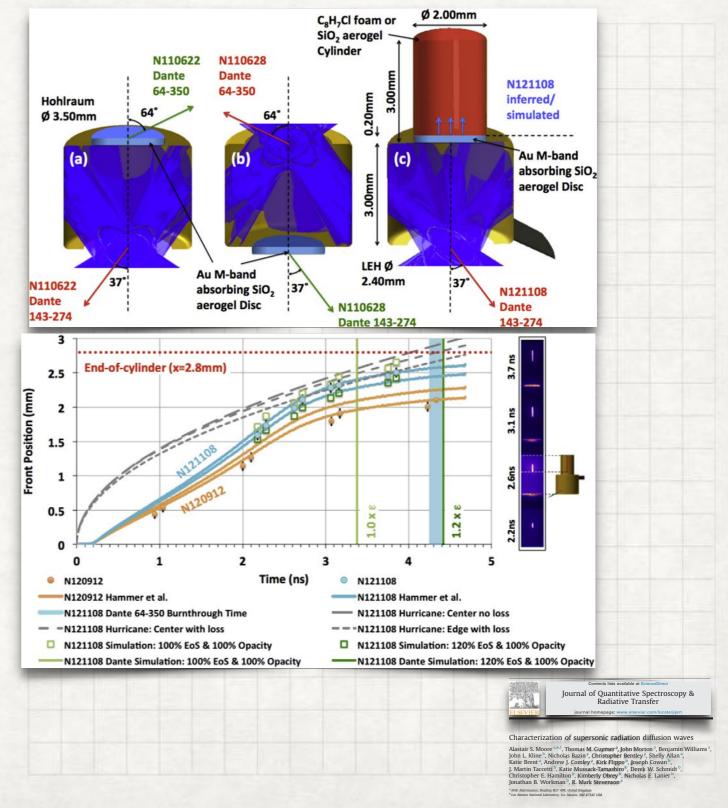
$$\nabla^2 T^4 = 0$$

- In 2-D Cartesian geometry, with x being the direction that the wave is propagating, the wavefront will then be a linear combination of cosines, that determine the curvature of the wavefront.
- Detailed analysis then gives a form for the curvature as a function of boundary conditions, etc., and an equation for the propagation of the wavefront.
- Hammer and Rosen also use the slow change behind the wavefront, but they use this to derive the results from changing boundary temperatures for 1-D problems, and solve problems regarding supersonic and subsonic diffusion waves.

### COMPARISONS WITH EXPERIMENT SHOW THESE MODELS ARE REASONABLE

### Improvement Is Possible

- A recent paper by Moore, et al. compares Marshak waves created at NIF with the different models of Hammer and Hurricane.
- There seems to be a gap between analytic theory and full-blown radiation hydrodynamics simulations.
- Is a simple, ordered, approximation to the radiative transfer in the experiment possible?



### MEANWHILE, 1-D MODELS WERE BEING DEVELOPED FOR TRANSPORT IN A DUCT

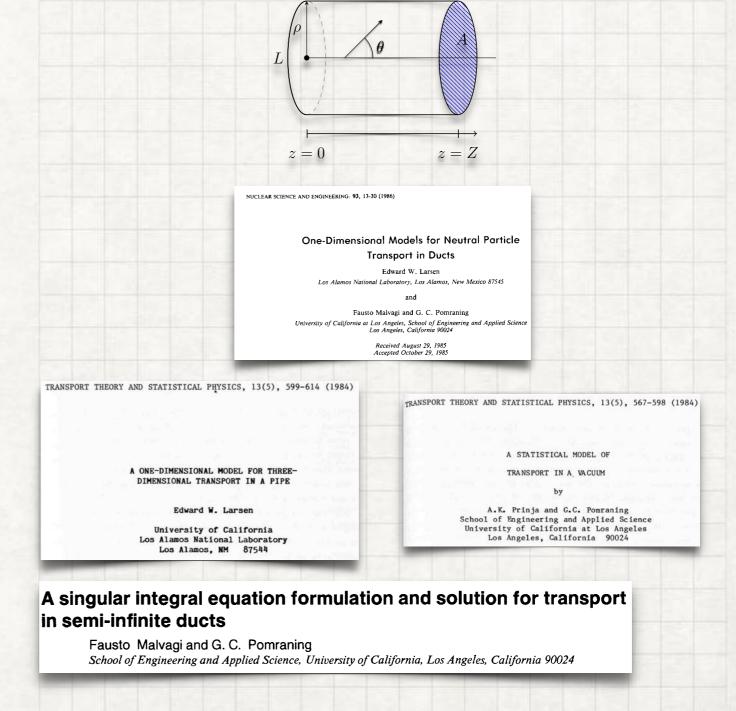
### Sometimes By The Same People

- Consider particles traveling in a duct of material that is surrounded by a wall that can reflect a fraction, c, of the particles back into the duct.
- Most of the models were developed for evacuated ducts where particles enter at one end.
- In an evacuated duct, the transport equation is written as

$$\mu \frac{\partial \psi}{\partial z} + \sqrt{1 - \mu^2} \left( \cos \gamma \frac{\partial \psi}{\partial x} + \sin \gamma \frac{\partial \psi}{\partial y} \right) = 0$$

 Using a Galerkin procedure, a simplified 1-D model can be derived

$$\mu \frac{\partial \Psi}{\partial z} + \sqrt{1 - \mu^2} \mathbf{A} \Psi = \frac{2c}{\pi} \mathbf{B} \int_{-1}^{1} \sqrt{1 - \mu'^2} \Psi(z, \mu') \, d\mu'$$
$$\psi(x, y, z, \mu, \gamma) = \sum_{n=1}^{N} b_n(x, y, \gamma) \Psi_n$$



# **EXTENSIONS TO THIS DUCT WORK**

- A quadratic expansion was introduced by Garcia, et al. (3 basis functions).
- Multigroup models for the transport also exist.
- Prinja modified the model to allow particles to re-enter the duct at different places (nonlocal reflection).
- Many papers on the efficient solution of the models.
- Models used in shielding and acoustics.

#### ON THE SOLUTION OF A NONLOCAL TRANSPORT EQUATION BY THE WIENER-HOPF METHOD

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Dedicated to Prof. M.M.R. Williams on the occasion of his 60th birthday

#### One-dimensional transport equation models for sound energy propagation in long spaces: Simulations and experiments

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The Third Basis Function Relevant to an Approximate Model of Neutral Particle Transport in Ducts

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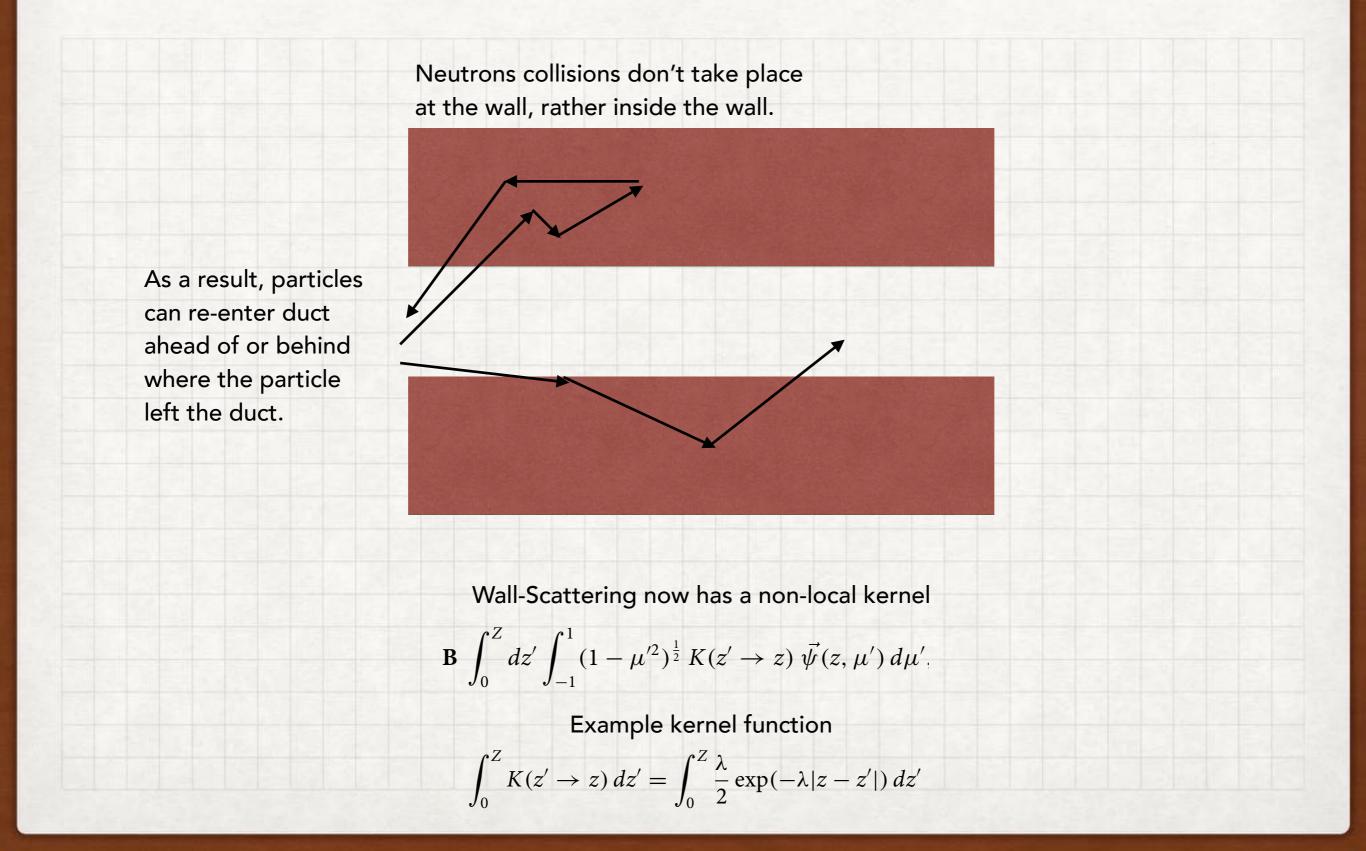
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#### Approximate One-Dimensional Models for Monoenergetic Neutral Particle Transport in Ducts with Wall Migration

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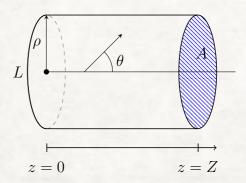
# WALL MIGRATION OF NEUTRONS



## THE CYLINDER IN THE MARSHAK WAVE PROBLEM IS A DUCT It Is Just Not An Evacuated Duct

- The radiative transfer in a cylinder is, in some sense, the opposite of the duct model.
  - Collisions take place in the cylinder and the walls have a reflection probably that could be zero.
- The 1-D duct models make no assumptions that the walls must scatter particles back into the domain.
- Furthermore, as pointed out early on in their history, there is no limitation to extending to non-evacuated ducts in the models.
  - They are just typically applied to evacuated regions.
- The curvature in the wave-front, time-dependence of drive, etc. could be included in the model.
- This would be a simplified model that captures the effects the 1-D diffusion models lack.

#### WE DEVELOP A MODEL FOR TIME-DEPENDENT TRANSPORT IN A SOLID CYLINDER



• We consider a linear transport problem:

 $\Psi(x,y,0,\mu,\varphi,t) = g_l(x,y,\mu,\varphi,t),$ 

$$\frac{\sigma_{\rm s}}{4\pi} \int\limits_{-1}^{1} d\mu' \int\limits_{0}^{2\pi} d\varphi' \,\Psi(x,y,z,\mu',\varphi',t) + \frac{Q}{4\pi}$$

 $\boldsymbol{\omega} = (\cos\varphi, \sin\varphi, 0)$ 

 $egin{aligned} \Psi(x,y,Z,\mu,arphi,t) &= g_r(x,y,\mu,arphi,t), & h(x,y) < 0, & \mu < 0, & \Psi(x,y,z,\mu,arphi,t) &= 0, & h(x,y) = 0, & \omega \cdot \mathbf{n} < 0, & & \end{aligned}$ 

 $\frac{1}{v}\frac{\partial\Psi}{\partial t} + (1-\mu^2)^{\frac{1}{2}} \left(\cos\varphi\frac{\partial}{\partial x} + \sin\varphi\frac{\partial}{\partial y}\right)\Psi + \mu\frac{\partial\Psi}{\partial z} + \sigma_{\rm t}\Psi =$ 

 We then propose an expansion in basis functions that contain the variation in x,y, and the azimuthal angle.

 $\Psi(x,y,z,\mu,arphi)pprox \sum \psi_i(z,\mu,t)b_i(x,y,arphi).$ 

Here  $I \leq 3$ . The basis functions are

 $b_1(x;y,arphi) = X$ 

 $b_2(x,y,arphi) = u[D(x,y,arphi) - v]$ 

 $b_3(x,y,arphi) = r[D(x,y,arphi) - v][D(x,y,arphi) - v - q] - r/u^2.$ 

## THE GALERKIN PROJECTION TO A 1-D MODEL

 The function D gives the distance from a point to the edge of the cylinder along the direction ω. For a cylinder this is

$$D(x, y, \varphi) = \mathbf{r} \cdot \omega + [(\mathbf{r} \cdot \omega)^2 + \rho^2 - x^2 - y^2]^{\frac{1}{2}}, \qquad \mathbf{r} = (x, y, 0)$$

• The basis expansion is substituted into the transport equation, and the resulting equation is integrated against the basis functions to get

$$\begin{split} \frac{1}{v} \frac{\partial \psi_i}{\partial t} + \mu \frac{\partial \psi_i}{\partial z} + \sigma_{\rm t} \psi_i + \sqrt{1 - \mu^2} \sum_{j=1}^3 a_{ij} \psi_j(z, \mu, t) &= \frac{\sigma_{\rm s}}{2} \phi_i(z, t) + Q_i, \\ Q_i &= \frac{1}{2\pi A} \int_R dx \, dy \int_0^{2\pi} d\varphi \, b_i(x, y, \varphi) \frac{Q}{4\pi}. \end{split}$$

- These equations are a set of coupled 1-D transport equations. The effective total cross-section depends on  $\mu$ .
- •The coupling does make the equations look like a multigroup system.

## THE MATRIX ELEMENTS ARE NOT NECESSARILY POSITIVE

From Garcia, Ono, And Veira (2000)

$$a_{11} = b_{11} = L/(\pi A) ,$$
  

$$a_{12} = b_{12} = u - uvL/(\pi A) ,$$
  

$$a_{21} = b_{21} = -uvL/(\pi A) ,$$
  

$$a_{22} = u^2 v^2 L/(\pi A) ,$$

$$b_{22} = -uv[u - uvL/(\pi A)]$$
.

$$a_{13} = b_{13} = -qr + (v^2 + qv - 1/u^2)rL/(\pi A)$$
  

$$a_{31} = b_{31} = (v^2 + qv - 1/u^2)rL/(\pi A) ,$$
  

$$a_{23} = (2r/u) - (v^2 + qv - 1/u^2)uvrL/(\pi A) ,$$
  

$$b_{23} = uv[qr - (v^2 + qv - 1/u^2)rL/(\pi A)] ,$$
  

$$a_{32} = -(v^2 + qv - 1/u^2)uvrL/(\pi A) ,$$
  

$$b_{32} = r(v^2 + qv - 1/u^2)[u - uvL/(\pi A)] ,$$
  

$$a_{33} = (v^2 + qv - 1/u^2)^2r^2L/(\pi A) ,$$
  
and

$$b_{33} = -r(v^2 + qv - 1/u^2) \times [qr - (v^2 + qv - 1/u^2)rL/(\pi A)] .$$

$$u = \left\{ \frac{1}{2\pi A} \int_R \int_0^{2\pi} \left[ D(x, y, \boldsymbol{\omega}) - v \right]^2 d\varphi dx dy \right\}^{-1/2}$$

$$v = \frac{1}{2\pi A} \int_R \int_0^{2\pi} D(x, y, \boldsymbol{\omega}) \, d\varphi \, dx \, dy \quad .$$

$$q = 8\rho \left[ \frac{9\pi}{5} (9\pi^2 - 64)^{-1} - \frac{2}{3\pi} \right]$$

$$r = \rho^{-2} \left[ 1 - \frac{576}{25} (9\pi^2 - 64)^{-1} \right]^{-1/2}$$

WE SOLVE THE EQUATIONS WITH A DISCRETE ORDINATES SCHEME Off-Diagonal Terms Are Updated Through Source Iteration

• We compute transport sweeps as

$$\mu_k \frac{\partial}{\partial z} \psi_{ik}^{\ell} + (\sigma_t^* + a_{ii}) \psi_{ik}^{\ell} = \sum_{i \neq j}^3 a_{ij} \sqrt{1 - \mu_k^2} \psi_{jk}^{\ell-1} + \frac{\sigma_s}{2} \phi_i^{\ell-1} + Q_{ik}^*$$

• k is the angle index, and superscript  $\ell$  is the iteration index. The asterisks denote changes made to write the time-dependent equation in quasi-steady form.

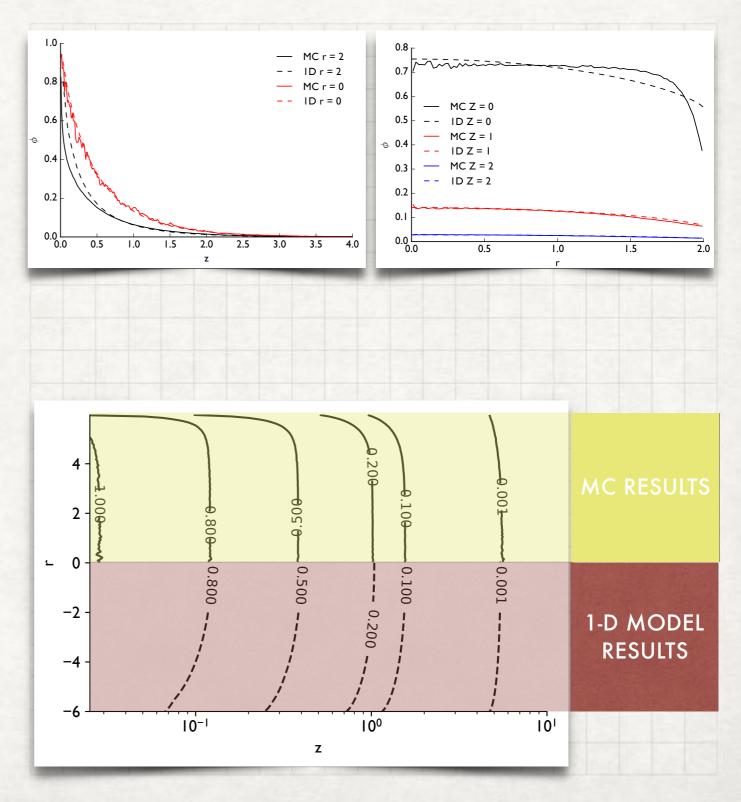
$$\sigma_{t}^{*} = \sigma_{t} + \frac{1}{v\Delta t} \qquad Q_{ik}^{*} = Q_{i} + \frac{\psi_{ik}^{\text{old}}}{v\Delta t}$$

 One could imagine developing acceleration strategies for these equations, but we have not needed them in our work to date.

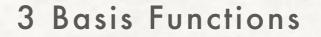
# **STEADY-STATE RESULTS**

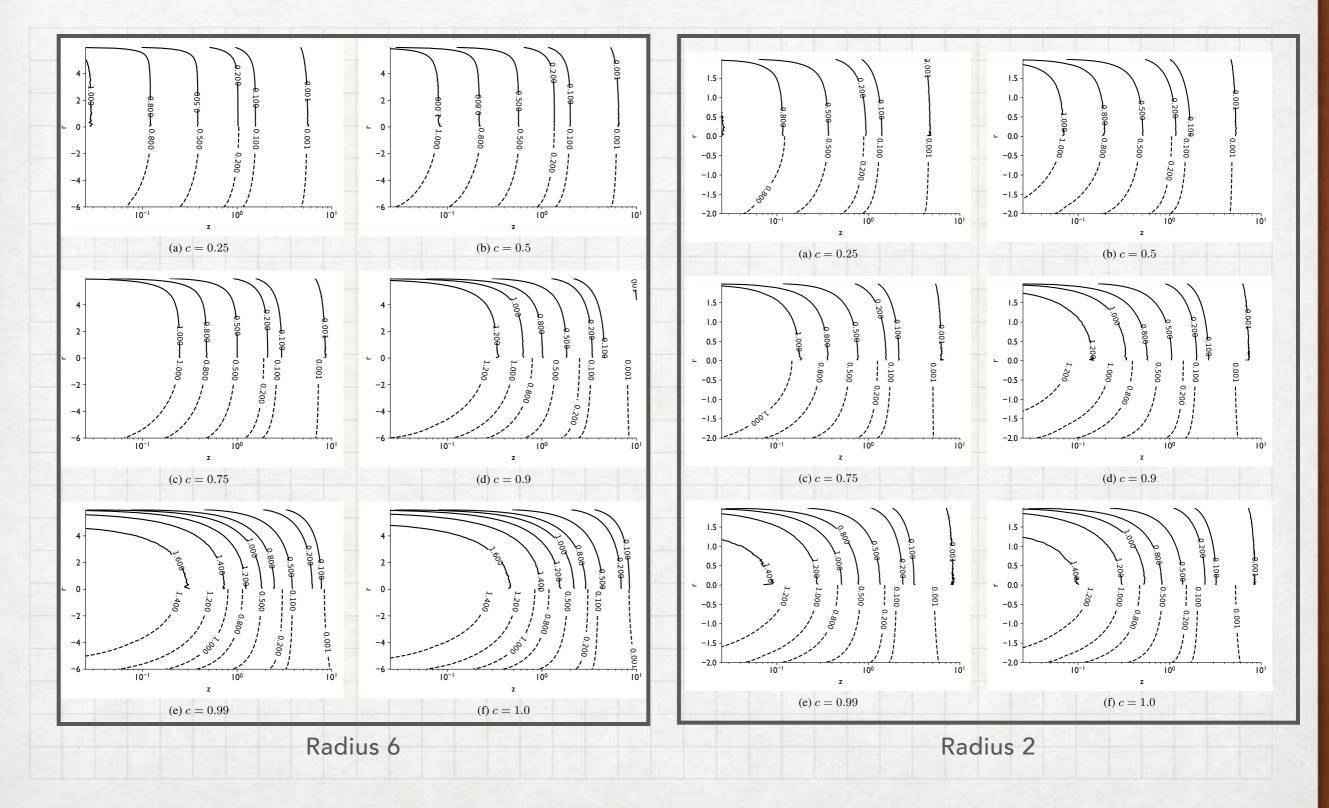
### Comparison With Monte Carlo

- We solve a problem of a cylinder of a single material with unit total cross-section and length 10.
- We vary the radius between 2 and 6, and the scattering ratio from 0 to 1.
- A unit incident, isotropic flux is imposed at z=0.
- Comparisons are made with calculations from Milagro from LANL.
- Contour maps will have MC results at positive r and 1-D results at "negative" r.



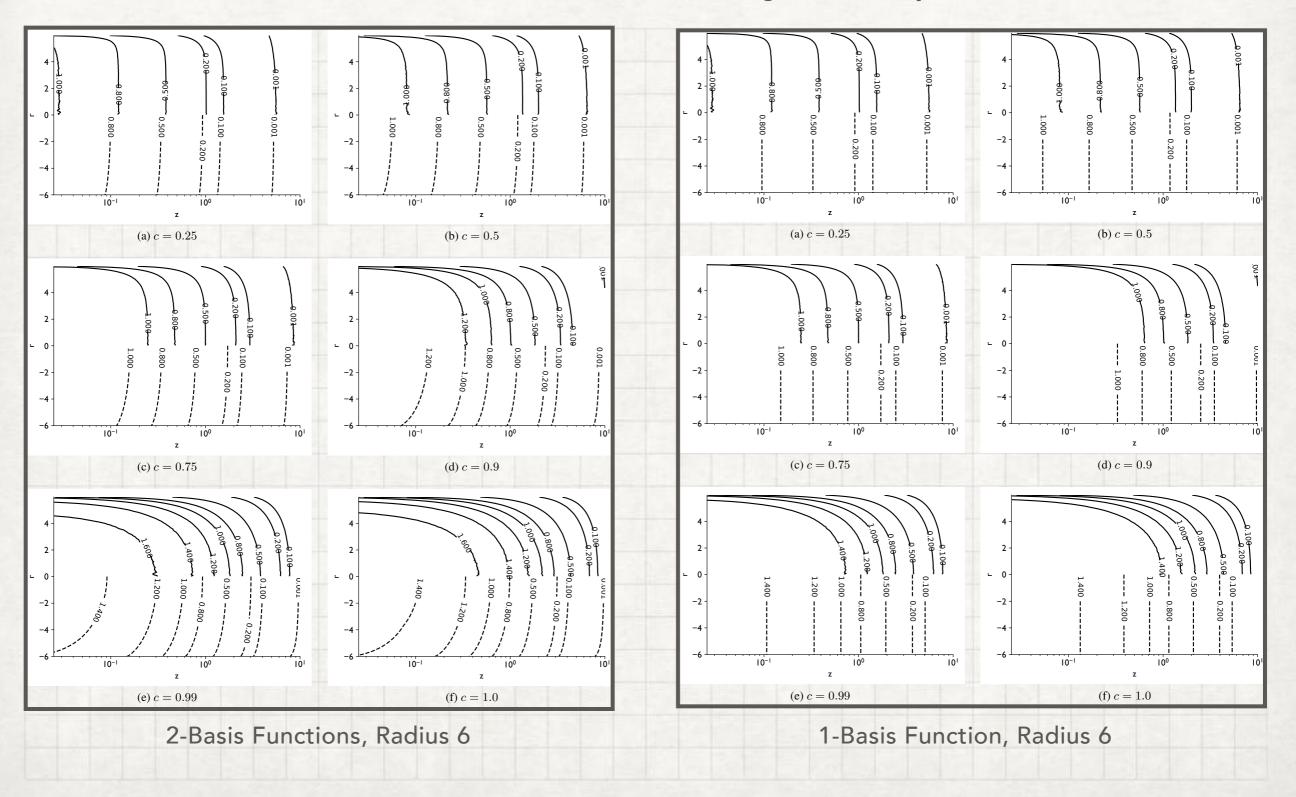
## 1-D MODELS PERFORM BETTER WITH LOW SCATTERING RATIO



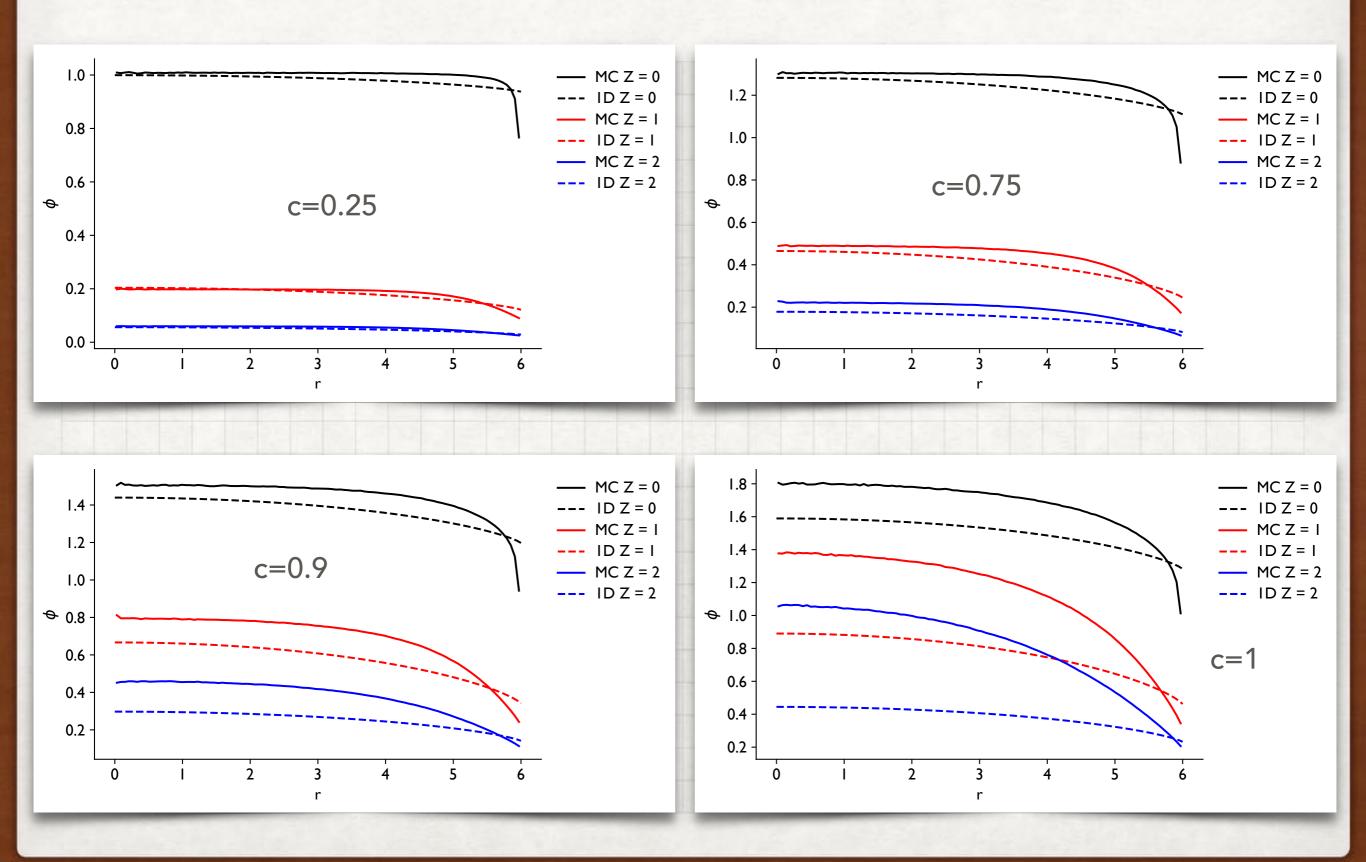


## THE QUADRATIC MODEL IS NECESSARY

2 And 1 Basis Functions Are Significantly Worse

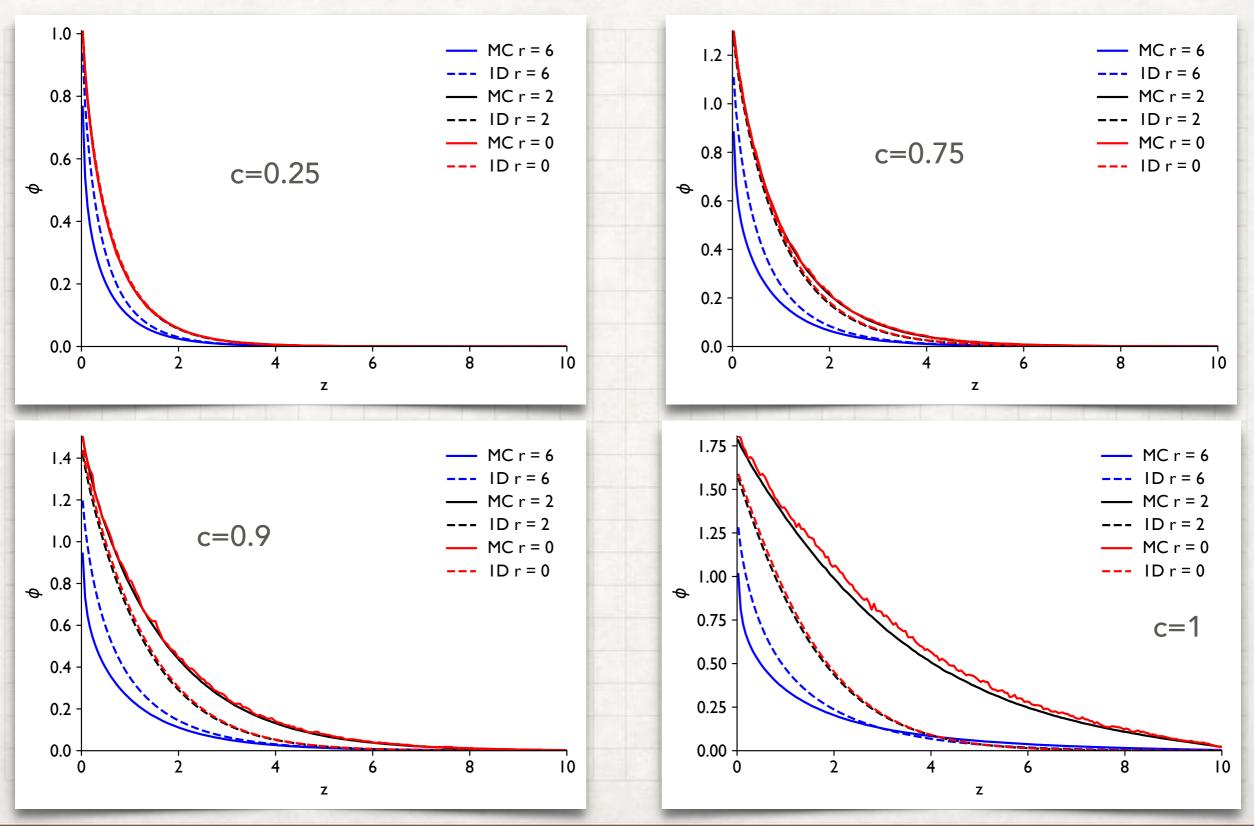


## **3 BASIS FUNCTION SOLUTIONS VERSUS RADIUS**



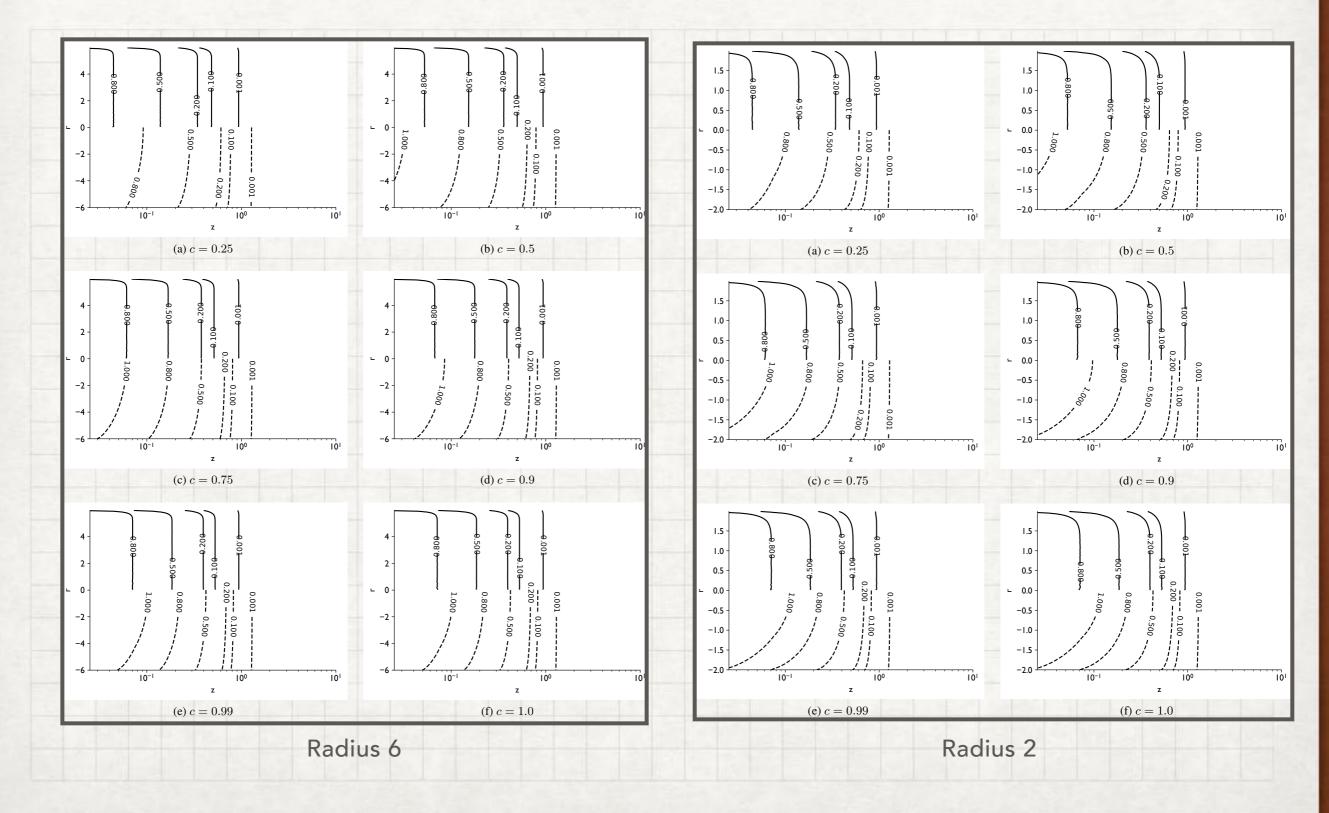
## **BIGGEST DISCREPANCY IS NEAR RADIAL EDGE**

3 Basis Function Solutions, R=6



## TIME-DEPENDENT SOLUTIONS HAVE THE OPPOSITE PROBLEM

3 Basis Functions Solutions At 1 Mean-Free Time Move Too Fast



### EXTENDING MODEL TO RADIATIVE TRANSFER PROBLEMS WILL INVOLVE COMPLICATIONS

### Non-Constant Cross-Sections

- Beyond adding the coupling to the material temperature equation, there are additional complications to solving the 2-D Marshak wave problem in a cylinder.
- Spatially dependent cross-sections will cause create additional coupling between the angular fluxes.
- In principle, these can all be handled.
- An interesting question is the diffusion limit of this model.
- Scaling the equations so that scattering is large, and absorption, timedependence, sources, and the correction terms are small, I get that the leading order solution satisfies

$$\frac{1}{v}\frac{\partial\phi_i^{(0)}}{\partial t} - \frac{\partial}{\partial z}\frac{1}{3\sigma_{\rm t}}\frac{\partial\phi_i^{(0)}}{\partial z} + \sigma_{\rm a}\phi_i^{(0)} + \frac{\pi}{4}\sum_{j=1}^3 a_{ij}\phi_j^{(0)} = 2Q_i.$$