

# The Spectral Volume Method as Applied to Transport Problems

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# Outline

- 1 Summary and Motivation
- 2 Derivation
  - Choice of Sub-Cell Partitioning
  - Properties Of The Spectral Volume Method
- 3 Numerical Results
  - Reed's Problem
  - Diffusive Problem
- 4 Conclusions and Future Work

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  - In such regions high-order reconstructions using large cells can be more efficient.
- Extra-unknowns, if they don't increase the communication burden, might only marginally increase the computational cost.

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- This can be thought of as a generalization of the simple corner balance and other sub-cell balance method previously presented.
- The term spectral is used here to note that the solution in each cell is reconstructed via polynomials in a similar way to a spectral method on a finite domain.

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  - In the hope of resolving a boundary layer between a diffusive and non-diffusive region.
- This is the topic of ongoing work.

# Derivation of the method

- We begin with the steady-state transport equation in slab-geometry, using discrete ordinates:

$$\mu_l \partial_x \psi_l + \sigma_t \psi_l = \frac{\sigma_s}{2} \langle \psi_l \rangle + \frac{Q}{2}, \quad l \in [1, L].$$

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- We then further partition each cell  $i$  into  $K$  sub-cells with width  $\Delta x_{i,k}$ .
- Averaging over a generic sub-cell  $k$  of cell  $i$  yields

$$\frac{\mu_l}{\Delta x_{i,k}} \left( \hat{\psi}_l^{i,k+1/2} - \hat{\psi}_l^{i,k-1/2} \right) + \sigma_t \psi_l^{i,k} = \frac{\sigma_s}{2} \langle \psi_l^{i,k} \rangle + \frac{Q^{i,k}}{2},$$

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- This polynomial is given by

$$p_l(x) = \sum_{k=1}^K \varphi_k(x) \psi_l^{i,k},$$

where

$$\varphi_k(x) = \prod_{q=1, q \neq k}^K \frac{x - x_{iq}}{x_{i,k} - x_{iq}}.$$

# Interfacial values

- We then use this polynomial to give the value of the  $\psi_l$  inside of cell  $i$ . Specifically, this polynomial gives the interfacial values between the sub-cells:

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- At the interface between cells we use the principle of upwinding to choose the value. Specifically,

$$\hat{\psi}_l^{i,k-1/2} = \begin{cases} p_l(x_{i-1/2}) & \mu_l < 0 \\ p_l^{i-1}(x_{i-1/2}) & \mu_l > 0 \end{cases} \quad \text{for } k = 1,$$

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- Using Gauss-Lobatto quadrature points to define the sub-cell edges has been shown to maintain convergence.
- For a generic cell this approach leads to

$$x_{i,k+1/2} = \frac{\Delta x_i}{2} \left( 1 - \cos \left( \frac{k\pi}{K} \right) \right), \quad k = 0, \dots, K.$$

# Sub-cell Edges

- The edges when define with the GL quadrature points are

K	Points
2	0, 0.5, 1
3	0, .25, .75, 1
4	0, 0.146447, 0.5, 0.853553, 1
5	0, 0.0954915, 0.345492, 0.654508, 0.904508, 1
6	0, 0.0669873, 0.25, 0.5, 0.75, 0.933013, 1
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- Notice how these points are clustered near the edges of the main cell.

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- If we multiply the balance equation for a sub-cell by  $\Delta x_{i,k}/\Delta x_i$  and sum over  $k = 1 \dots K$ , we get

$$\frac{\mu_l}{\Delta x_i} \left( \hat{\psi}_l^{i,K+1/2} - \hat{\psi}_l^{i,1/2} \right) + \sigma_t \sum_{k=1}^K \frac{\Delta x_{i,k}}{\Delta x_i} \psi_l^{i,k}, = \frac{\sigma_s}{2} \left\langle \sum_{k=1}^K \frac{\Delta x_{i,k}}{\Delta x_i} \psi_l^{i,k} \right\rangle + \frac{\bar{Q}^i}{2},$$



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- To show conservation over the entire domain, we multiply this equation by  $\Delta x_i$  and sum over all cells to get

$$-\mu_l \left( \hat{\psi}_l^{I,K+1/2} - f_l \right) + \sum_i \Delta x_i \left( \frac{\sigma_s}{2} \langle \bar{\psi}_l^i \rangle - \sigma_t \bar{\psi}_l^i + \frac{\bar{Q}^i}{2} \right) = 0, \quad \mu > 0,$$

and

$$-\mu_l \left( g_l - \psi_l^{1,1/2} \right) + \sum_i \Delta x_i \left( \frac{\sigma_s}{2} \langle \bar{\psi}_l^i \rangle - \sigma_t \bar{\psi}_l^i + \frac{\bar{Q}^i}{2} \right) = 0, \quad \mu < 0.$$

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- We can see this by writing out the equations for  $\mu > 0$  for a generic cell with  $K = 2$  and  $\Delta x_i = 2\Delta x_{i,k}$ :

$$\frac{\mu_l}{\Delta x_i} \left( (\psi_l^{i,2} + \psi_l^{i,1}) - (3\psi_l^{i-1,2} - \psi_l^{i-1,1}) \right) + \sigma_t \psi_l^{i,1} = \frac{\sigma_s}{2} \langle \psi_l^{i,1} \rangle + \frac{Q^{i,k}}{2},$$

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- This gives a corner balance scheme where the value at the cell-center and at the cell edges are linear interpolations from the sub-cell values.

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- Static adaptivity using the spectral volume method has been shown to be successful in results from multidimensional computational fluid dynamics simulations (Wang, 2004).
- Furthermore, the interpolation inside each cell can be used to deal with dendritic meshes that arise in adaptive mesh refinement calculations.

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  - Each cell requires the incoming flux at each incoming face and communicates its outgoing flux at the appropriate faces.
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  - This has been demonstrated in recent magnetohydrodynamics methods, possibly making the larger values of  $K$  “free”.

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- If we scale the original, discrete transport equation by a small, positive parameter  $\epsilon$  as

$$\frac{\epsilon\mu_l}{\Delta x_{i,k}} \left( \hat{\psi}_l^{i,k+1/2} - \hat{\psi}_l^{i,k-1/2} \right) + \sigma_t \psi_l^{i,k} = \frac{1}{2} (\sigma_t - \epsilon^2 \sigma_a) \langle \psi_l^{i,k} \rangle + \frac{\epsilon^2 Q^{i,k}}{2}.$$

and expand  $\psi$  in a power series in  $\epsilon$

$$\psi_l^{i,k} = \sum_{j=0}^{\infty} \epsilon^j \psi_l^{(j),i,k},$$

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- For the case of  $K = 2$ , if we turn the crank to get the diffusion equation, we get the consistent, diffusion discretization:

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  - Numerical results demonstrate the robustness of these methods.

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# Reed's Problem

- Reed's problem has several different material regions

Vacuum Bound.	Scattering Region $\Sigma_a = 0.1$ $\Sigma_s = 0.9$		Vacuum	Absorber $\Sigma_a = 5$ $\Sigma_s = 0$ $Q = 0$	Strong Source $\Sigma_a = 50$ $\Sigma_s = 0$ $Q = 50$	Reflect. Bound
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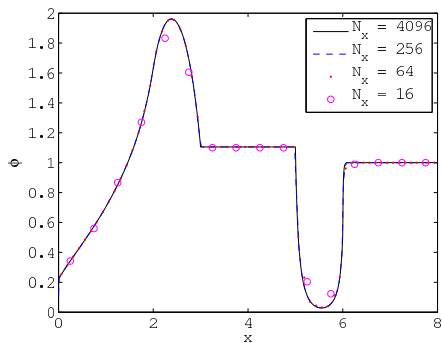
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- We'll use  $S_8$  and a sweep-based GMRES scheme to solve the SV equations.

# Results with $K = 2, 3$

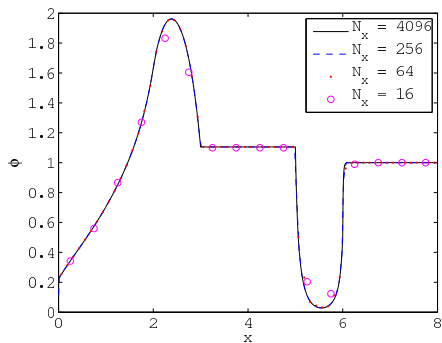
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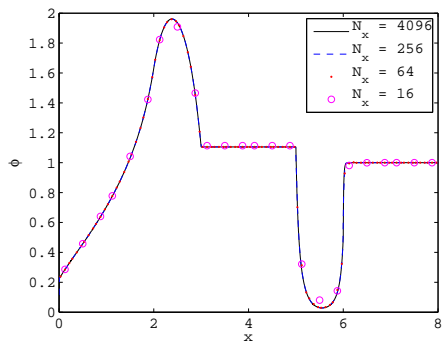


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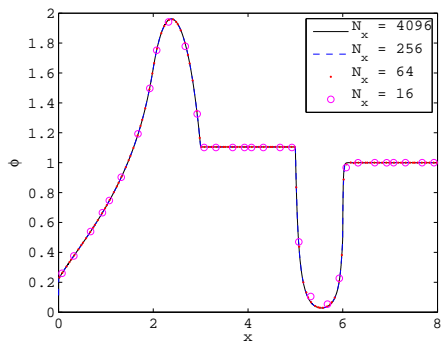
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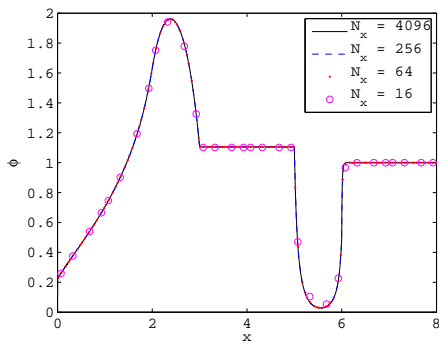
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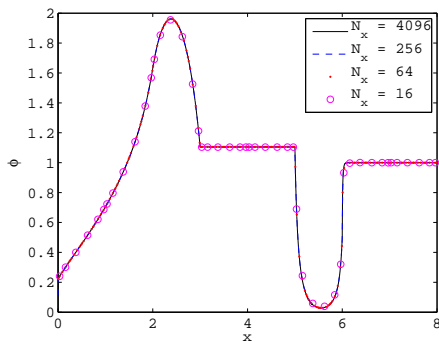


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- This problem is almost ideal for this method as the scalar flux is only non-smooth at the material interfaces.

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# Diffusive Problem (with boundary layer)

- This problem has a strong absorber next to a diffusive region

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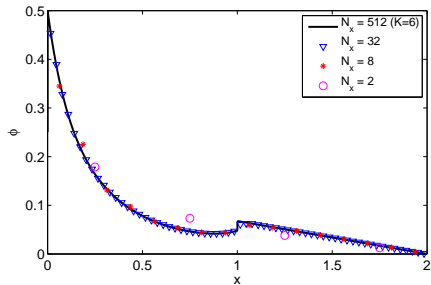
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- For comparison we use a  $K = 6$  and  $N_x = 512$  solution as a reference ( $\max \Delta x_{i,k} = .00097656$ ).

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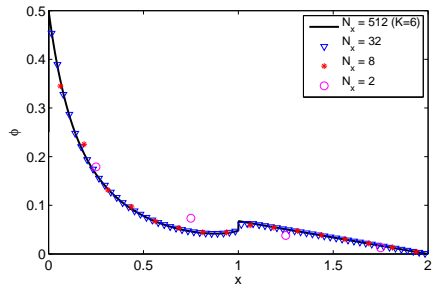
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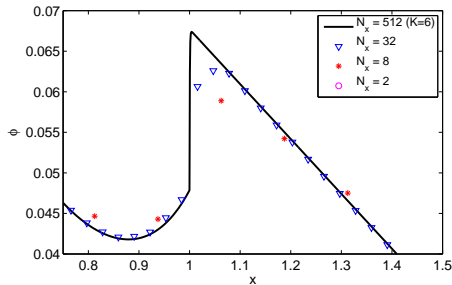


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Detail



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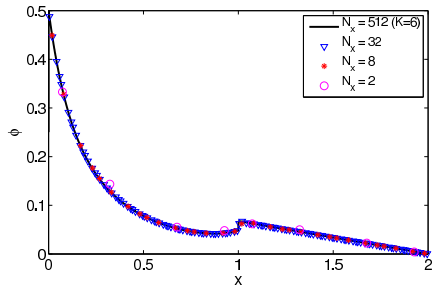
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- Away from the boundary layer the solution has the correct slope for  $N_x = 8$  and 32.

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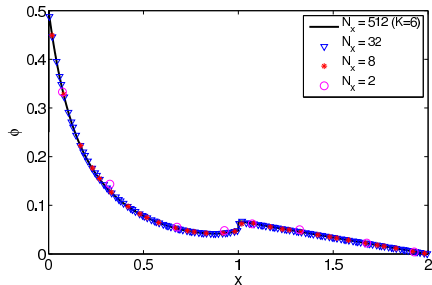
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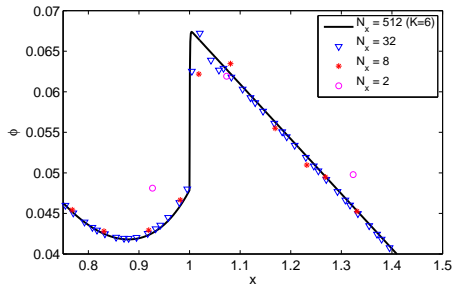


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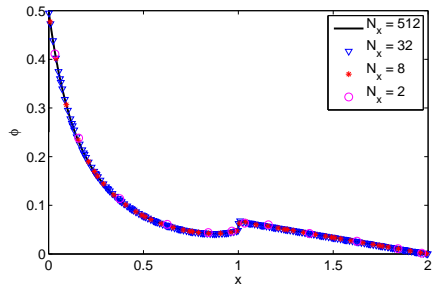
- For  $K = 4$  does a much better job resolving the solution near the interface, including the maximum scalar flux for  $N_x \geq 32$ .
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  - These are due to interpolating across this sharp change.



# Results for $K = 6$

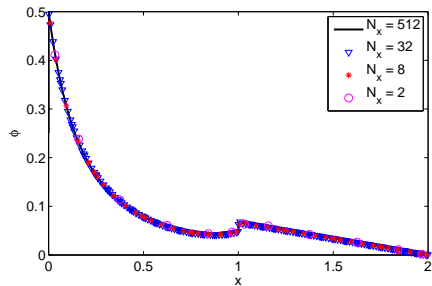
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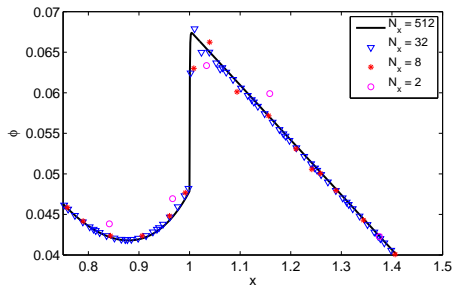


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- Might be a good candidate for local parallelism.

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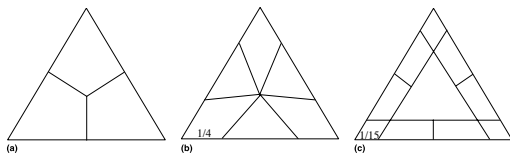


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- This might necessitate fancier reconstruction schemes.

## 2-D Spectral Volume on Triangles

- Here's how Wang (2004) divided a triangle into subcells.



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# Acknowledgments

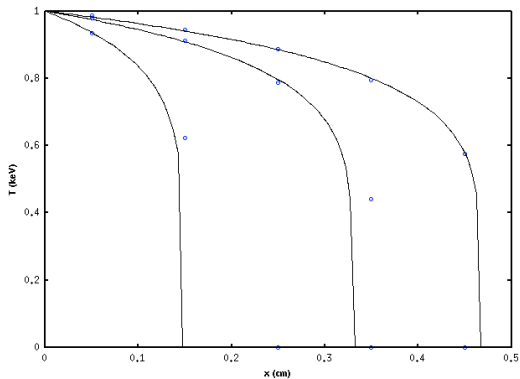
- Thanks to Cory Hauck at Oak Ridge National Lab for showing me this method and getting me interested in it.

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# Marshak Wave

- This method also works for time-dependent thermal radiative transfer problems.





# Marshak Wave

- This method also works for time-dependent thermal radiative transfer problems.
- This figure shows the  $K = 6$  solution with 5 cells and the analytic diffusion solution at  $t = 10, 50,$  and  $100$  ns for a problem with a 1 keV incident source and  $\sigma = 300/T^3$ .

